

Q2V

Driving Quality

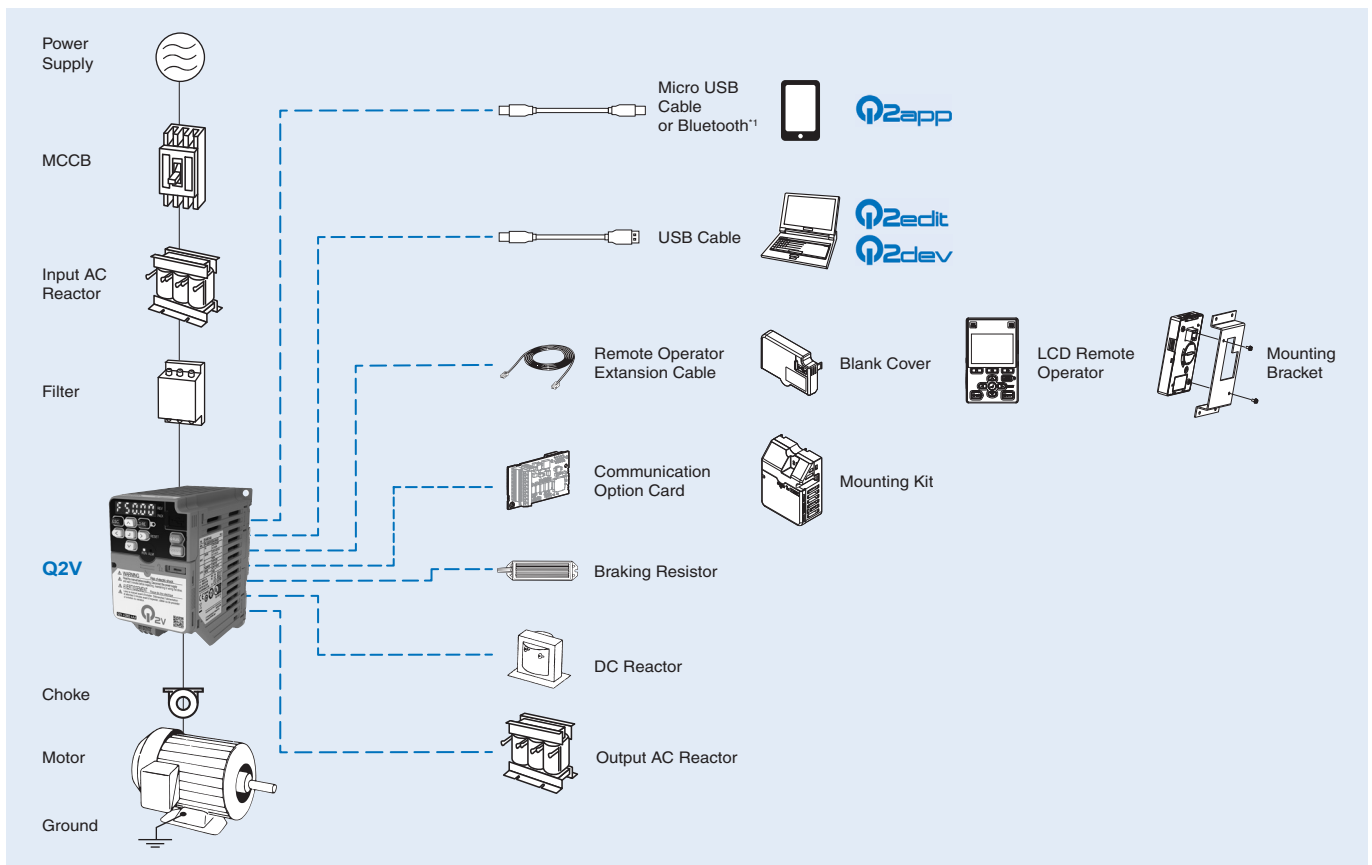
- Flexible motor control: IM, PM, SynRM
- V/f and Sensorless vector motor control
- Speed control and torque limit in open loop
- Embedded STO (Safe Torque Off) safety function, SIL3/PLe
- Built-in C1/C2/C3 class EMC filter
- Built-in braking transistor
- Quick and easy setup with optional remote LCD keypad with Micro SD card for data storage
- 24 VDC power supply input for control board
- Communication options: EtherCAT, EtherNet/IP, PROFINET, POWERLINK
- Up to 5 Q2V with a single communication option card
- Q2dev: Intuitive drag and drop programming
- Q2app: Mobile app for setup and monitoring
- CE, UL, cUL, EAC, REACH, RoHS

Ratings

- 200 V class single-phase: 0.1 to 4 kW
- 200 V class three-phase: 0.1 to 22 kW
- 400 V class three-phase: 0.37 to 30 kW



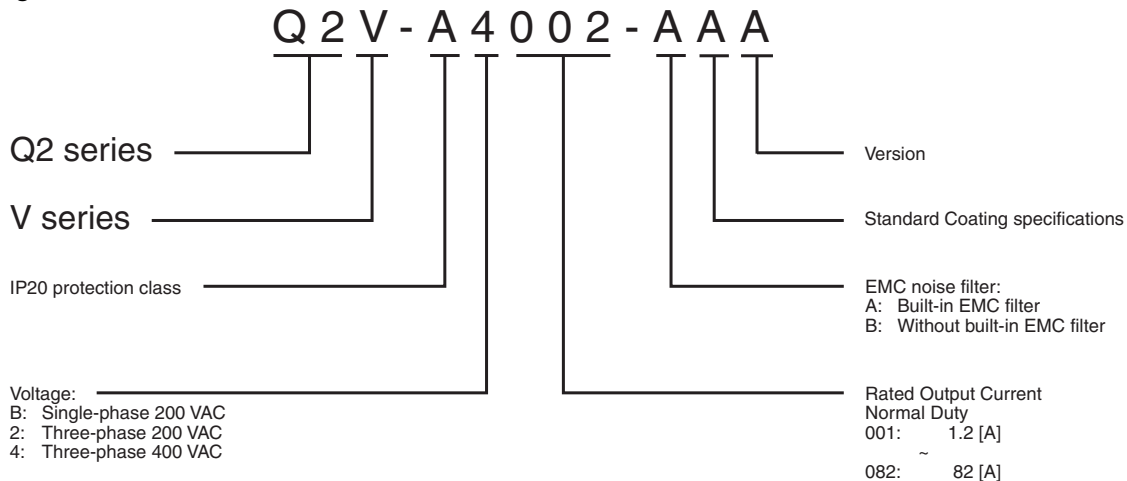
System configuration



*1 With optional LCD remote operator model with Bluetooth.

Specifications

Type designation



200 V class

Single-phase: Q2V-A□		Duty rating	B001	B002	B004	B006	B010	B012	B018	—	—	—	—	—	
Three-phase: Q2V-A□			2001	2002	2004	2006	2010	2012	—	2021	2030	2042	2056	2070	2082
Max. applicable motor output (kW)	HD ^{*1}		0.1	0.25	0.55	1.1	1.5	2.2	4.0	4.0	5.5	7.5	11	15	18.5
	ND ^{*2}		0.18	0.37	0.75	1.1	2.2	3.0	—	5.5	7.5	11	15	18.5	22
Drive capacity (kVA) ^{*3}	HD		0.3	0.6	1.1	1.9	3.0	4.2	6.7	6.7	9.5	12.6	17.9	22.9	28.6
	ND		0.5	0.7	1.3	2.3	3.7	4.6	—	8.0	11.4	16	21.3	26.7	31.2
Rated output current (A)	HD		0.8	1.6	3.0	5.0	8.0	11	17.6	17.6	25	33	47	60	75
	ND		1.2	1.9	3.5	6.0	9.6	12.2	—	21	30	42	56	70	82
Overload tolerance ^{*4}		<ul style="list-style-type: none"> HD: 150% of the rated output current for 60 seconds ND: 110% of the rated output current for 60 seconds 													
Carrier frequency ^{*5} (without derating the drive capacity)		<ul style="list-style-type: none"> HD: 10 kHz ND: 2 kHz HD: 8 kHz ND: 2 kHz 													
Max. output voltage		Proportional to input voltage: 200-240 V													
Max. output frequency		<ul style="list-style-type: none"> EZOLV: 120 Hz AOLV/PM: 270 Hz V/f, OLV, OLV/PM: 590 Hz 													
Rated voltage and frequency		<ul style="list-style-type: none"> 3-phase AC power supply 200-240 V at 50/60 Hz DC power supply 270-340 VDC 													
Allowable voltage fluctuation		-15% to +10%													
Allowable frequency fluctuation		±5%													
Input Power (kVA)	HD		0.3	0.7	1.3	2.7	3.4	5.0	9.2	8.7	11.0	17.0	24.0	31.0	44.0
	ND		0.5	1.2	1.8	3.3	4.9	6.4	—	11.0	17.0	24.0	31.0	37.0	52.0
Weight (kg)			0.5	0.8	0.9	1.5	2.9	2.0	3.4	3.6	5.5	7.5	8.0		

- *1. The maximum applicable motor output complies with 208 V motor ratings as specified in NEC Table 430.250. The rated output current of the drive output amps must be equal to or more than the motor rated current.
- *2. The maximum applicable motor output is based on 4-pole, general-purpose 220 V motor ratings. The rated output current of the drive output amps must be equal to or more than the motor rated current.
- *3. The rated output capacity is calculated with a rated output voltage of 220 V.
- *4. Derating may be necessary for applications that start and stop frequently.
- *5. Derate the drive capacity to use values to 15 kHz maximum.

Note: EMC class of single-phase 200 V drives with built-in filter is C1 for 10 m motor cable (except AB018 model).
 EMC class of 3-phase 200 V drives is C3 for 20 m motor cable.

400 V class

Three-phase: Q2V-A□		Duty rating	4001	4002	4004	4005	4007	4009	4012	4018	4023	4031	4038	4044	4060
Max. applicable motor output (kW) ^{*1}	HD		0.37	0.55	1.1	1.5	2.2	3.0	4.0	5.5	7.5	11	15	18.5	22
	ND		0.37	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15	18.5	22	30
Drive capacity (kVA) ^{*2}	HD		0.9	1.4	2.6	3.7	4.3	5.6	7.0	11.3	13.7	18.3	23.6	29.7	34.3
	ND		0.9	1.6	3.1	4.1	5.4	6.8	9.1	13.3	17.8	23.6	29	33.5	45.7
Rated output current (A)	HD		1.2	1.8	3.4	4.8	5.6	7.3	9.2	14.8	18	24	31	39	45
	ND		1.2	2.1	4.1	5.4	7.1	8.9	11.9	17.5	23.4	31	38	44	60
Overload tolerance ^{*3}		<ul style="list-style-type: none"> HD: 150% of the rated output current for 60 seconds ND: 110% of the rated output current for 60 seconds 													
Carrier frequency ^{*4} (without derating the drive capacity)		<ul style="list-style-type: none"> HD: 8 kHz ND: 2 kHz 													
Max. output voltage		Proportional to input voltage: 380-480 V													
Max. output frequency		<ul style="list-style-type: none"> V/f, OLV, OLV/PM: 590 Hz AOLV/PM: 270 Hz EZOLV: 120 Hz 													

Three-phase: Q2V-A□		Duty rating	4001	4002	4004	4005	4007	4009	4012	4018	4023	4031	4038	4044	4060
Power supply	Rated voltage and frequency	• 3-phase AC power supply 380-480 V at 50/60 Hz													
	Allowable voltage fluctuation	-15% to +10%													
	Allowable frequency fluctuation	±5%													
	Input Power (kVA)	HD	1.1	1.6	2.9	4.0	5.5	7.5	9.5	14	18	27	36	47	55
	ND	1.1	1.9	3.9	5.4	7.4	8.6	13	18	22	35	40	55	74	
Weight (kg)			0.8	0.9	1.5				2.0	3.0	3.2	4.6	4.8	6.5	

- *1. The maximum applicable motor output complies with 380 V motor ratings as specified in Annex G of IEC 60947-4-1. The rated output current of the drive output amps must be equal to or more than the motor rated current.
- *2. The rated output capacity is calculated with a rated output voltage of 440 V.
- *3. Derating may be necessary for applications that start and stop frequently.
- *4. Derate the drive capacity to use values to 15 kHz maximum.

Note: EMC class of 3-phase 400 V drives with built-in filter is C2 for 20 m motor cable.

Common specifications

Model number Q2V-A□		Specifications
Control functions	Control methods	V/f Control (V/f), Open Loop Vector Control (OLV), Open Loop Vector Control for PM (OLV/PM), Advanced Open Loop Vector Control for PM (AOLV/PM), EZ Open Loop Vector Control (EZOLV)
	Frequency control range	<ul style="list-style-type: none"> • V/f, OLV and OLV/PM: 0.01 Hz to 590 Hz • AOLV/PM: 0.01 Hz to 270 Hz • EZOLV: 0.01 Hz to 120 Hz
	Frequency tolerance	<ul style="list-style-type: none"> • Digital inputs: ±0.01% of the max. output frequency (-10 to +40 °C) • Analog inputs: ±0.1% of the max. output frequency (25 ±10 °C)
	Frequency setting resolution	<ul style="list-style-type: none"> • Digital inputs: 0.01 Hz • Analog inputs: 1/2048 of the max. output frequency (11-bit signed)
	Output frequency resolution	0.001 Hz
	Frequency setting signal	<ul style="list-style-type: none"> • Main speed freq reference: 0 to 10 VDC (20 kΩ), 4 to 20 mA (250 Ω), 0 to 20 mA (250 Ω) • Main speed reference: Pulse train input (max. 32 kHz)
	Starting torque ^{*1}	<ul style="list-style-type: none"> • V/f: 150%/3 Hz • OLV: 150%/1 Hz • OLV/PM: 100%/5% speed • AOLV/PM: 100%/0 min⁻¹ (when high frequency injection is enabled) • EZOLV: 100%/10% speed
	Speed control range	<ul style="list-style-type: none"> • V/f: 1:40 • OLV: 1:100 • OLV/PM: 1:10 • AOLV/PM: 1:100 (when high frequency injection is enabled) • EZOLV: 1:10
	Zero speed control	Possible in AOLV/PM control method
	Torque limits	Parameter settings allow different limits in four quadrants in these control methods: OLV, AOLV/PM, EZOLV
Accel/Decel Time	0.0 to 6000.0 s (the drive can set four pairs of different acceleration and deceleration times)	
Control functions	Braking torque	<p>Approximately 20%</p> <p>Approximately 125% with a dynamic braking option</p> <p>Short-time average deceleration torque:</p> <ul style="list-style-type: none"> • Motor output 0.1/0.2 kW: over 150% • Motor output 0.4/0.75 kW: over 100% • Motor output 1.5 kW: over 50% • Motor output 2.2 kW and larger: over 20%, • Overexcitation Braking/High Slip Braking allow for approximately 40% <p>Short-time average deceleration torque refers to the torque needed to decelerate the motor (uncoupled from the load) from the rated speed to zero. Motor characteristics can change the actual specifications.</p> <p>Motor characteristics change the continuous regenerative torque and short-time average deceleration torque for motors of 2.2 kW or higher.^{*2}</p>
	V/f characteristics	Select from 15 pre-defined V/f patterns or a user-set V/f pattern
Functionality	Main control functions	Feed Forward Control, Restart After Momentary Power Loss, Speed Search, Overtorque Detection, Torque Limit, 17 Step Speed (max.), Accel/Decel Switch, S-curve Acceleration/Deceleration, 3-wire Sequence, Auto-Tuning (Rotational and Stationary), Dwell Function, Cooling Fan ON/OFF Switch, Slip Compensation, Torque Compensation, Frequency Jump, Upper/Lower Limits for Frequency Reference, DC Injection Braking at Start and Stop, Overexcitation Braking, High Slip Braking, PID Control (with Sleep Function), Energy Saving Control, MEMOBUS/Modbus Communications (RS-485 max, 115.2 kbps), Auto Restart, Application Presets, DriveWorksEZ (customized functions), Parameter Backup Function, Online Tuning, KEB, Overexcitation Deceleration, Overvoltage Suppression, High Frequency Injection.

Protection functions	Motor	Electronic thermal overload protection
	Momentary overcurrent	Drive stops when the output current exceeds 200% of the HD output current
	Overload	Drive stops when the output current exceeds 150% of the HD output current or 110% of the ND output current for 60 seconds ^{*3}
	Overvoltage	200 V class: Stops when the DC bus voltage is more than approximately 410 V 400 V class: Stops when the DC bus voltage is more than approximately 820 V
	Undervoltage	Single-phase 200 V class: Stops when the DC bus voltage decreases to less than approximately 160 V Three-phase 200 V class: Stops when the DC bus voltage decreases to less than approximately 190 V Three-phase 400 V class: Stops when the DC bus voltage decreases to less than approximately 380 V
	Momentary power loss ride-thru	Stops when power loss is longer than 15 ms. Continues operation if power loss is shorter than 2 s (depending on parameter settings). Stop time may be shortened depending on the load and motor speed. Drive capacity will change the continuous operation time. A momentary power loss recovery unit is necessary to continue operation through a 2 s power loss on models 2001 to 2042 and 4001 to 4023.
	Heatsink overheat	Protected by thermistor
	Stall prevention	Stall prevention is available during acceleration, deceleration and during run
	Ground fault	Electronic circuit protection This protection detects ground faults during run. The drive will not provide protection when there is a low-resistance ground fault for the motor cable or terminal block or energizing the drive when there is a ground fault.
	DC Bus charge LED	Charge LED illuminates when DC bus voltage is more than 50 V.
Environment	Area of use	Indoor (no corrosive gas, dust, etc...)
	Power supply	Overvoltage Category III
	Ambient temperature	-10°C to +50°C
	Humidity	95% RH or less (without condensation)
	Storage temperature	-20°C to +70°C (short-term temperature during transportation)
	Surrounding area	Pollution degree 2 or less Install the drive in an area without: <ul style="list-style-type: none"> • Oil mist, corrosive or flammable gas or dust • Metal powder, oil, water or other unwanted materials • Radioactive materials or flammable materials, including wood • Harmful gas or fluids • Salt • Direct sunlight
	Altitude	Up to 1000 meters max. (output derating of 1% per 100 m above 1000 m, max. 3000 m)
	Vibration	<ul style="list-style-type: none"> • 10 Hz to 20 Hz: 1G (9.8 m/s²) • 20 Hz to 55 Hz: 0.6G (5.9 m/s²)
Installation orientation	Install the drive vertically for sufficient airflow to cool the drive.	
Safety standard	<ul style="list-style-type: none"> • UL61800-5-1 • EN61800-3 • EN61800-5-1 • Two Safe Disable inputs and one EDM output according to ISO/EN13849-1 Cat.III PL_e, IEC/EN61508 SIL3 	
Protection design^{*4}	Open chassis type: IP20	

*1. Correctly select drive capacity for this starting torque in these control methods: OLV, AOLV/PM.

*2. Set L3-04 to 0 (Stall Prevention during Decel = Disabled) when operating the drive with a regenerative converter, regenerative unit, braking unit, braking resistor or braking resistor unit. Failure to obey could prevent the drive from stopping in the specified deceleration time and cause serious injury or death.

*3. The drive can trigger the overload protection function within the overload tolerance if the output frequency is less than 6 Hz. Do not allow the overload more than once every ten minutes.

*4. Install an UL Type 1 kit on an Open-chassis type (IP20) to convert the drive to a Enclosed wall-mounted type (UL Type 1).

Dimensions

Q2V drive

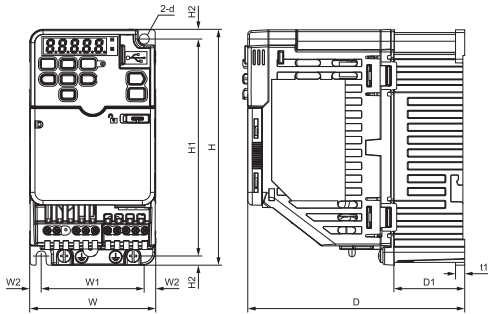


Figure 1

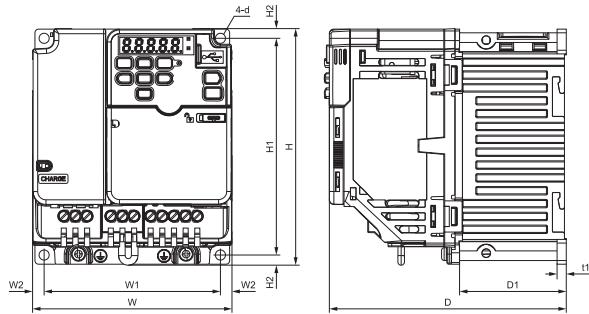


Figure 2

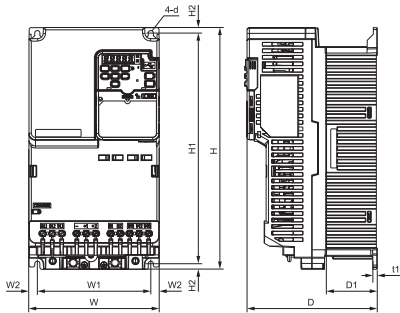


Figure 3

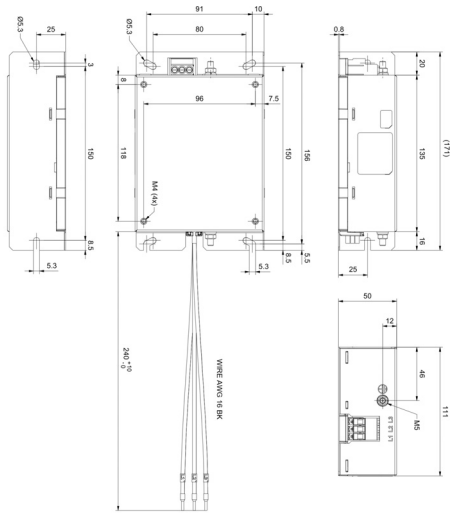
Models with built-in EMC filter

Voltage	Drive model	Fig.	Dimensions (mm)														
			W	W1	W2	H	H1	H2	D	D1	t1	d					
Single-phase 200 V	B001-A, B002-A	1	68	56	6	128	118	5	116	6.5	3	M5					
	158								38.5								
	B004-A	2	108	96	6	128	118	5	182.5	56.5	5	M5					
	B006-A								199	65							
	B010-A								203	65							
B012-A	140	128															
Three-phase 200 V	2001-A, 2002-A	1	68	56	6	128	118	5	116	6.5	3	M5					
	2004-A								148	38.5							
	2006-A								168	58.5							
	2010-A	2	108	96	6	128	118	5	174	56.5	5	M5					
	2012-A								182.5	65							
	2021-A	140	128						193	65							
	2030-A, 2042-A	3	140	122	9	260	248	6	196	55	5	M5					
	2056-A												180	160	10	300	284
2070-A, 2082-A	220												192	14	350	336	7
Three-phase 400 V	4001-A	2	108	96	6	128	118	5	126	8.5	5	M5					
	4002-A								144	26.5							
	4004-A								182.5	56.5							
	4005-A, 4007-A, 4009-A								199	65							
	4012-A	140	128						193	65							
	4018-A, 4023-A	3	140	122	9	260	248	6	196	55	5	M5					
	4031-A, 4038-A												180	160	10	300	284
4044-A, 4060-A	190													15	350	336	7

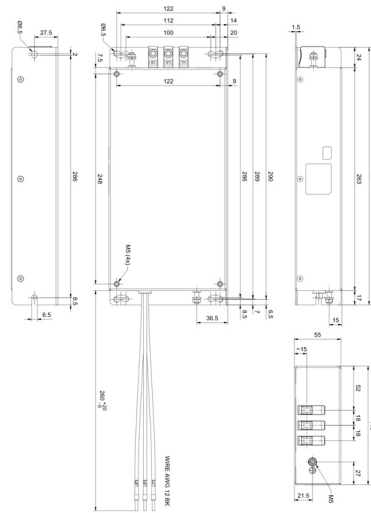
Models without built-in EMC filter

Voltage	Drive model Q2V-A□	Fig.	Dimensions (mm)														
			W	W1	W2	H	H1	H2	D	D1	t1	d					
Single-phase 200 V	B001-B	1	68	56	6	128	118	5	76	6.5	3	M5					
	B002-B								118	38.5							
	B004-B	2	108	96	137.5	56.5	5										
	B006-B																
	B010-B																
	B012-B							140	128								
B018-B	170	158	163	65													
Three-phase 200 V	2001-B	1	68	56	6	128	118	5	76	6.5	3	M5					
	2002-B								108	96			137.5	56.5			
	2004-B	2	108	96	129	56.5	5										
	2006-B																
	2010-B																
	2012-B							140	128	143	65						
	2021-B	3	140	122	9	260	248	6	140	55	5						
	2030-B																
	2042-B	3	180	160	10	300	284	8	143	78							
	2056-B																
	2070-B								220		192		14	350	336	7	187
	2082-B								M6								
	Three-phase 400 V	4001-B	2	108	96	6	128	118		5	81		8.5	5	M5		
		4002-B							99		26.5						
4004-B		2	108	96	137.5	56.5	5										
4005-B																	
4007-B																	
4009-B								154									
4012-B		3	140	128	9	260	248	6	143	65	5						
4018-B																	
4023-B		3	180	160	10	300	284	8	143	78							
4031-B																	
4038-B									190		15	350	336	7		204	94
4044-B									M6								
4060-B																	

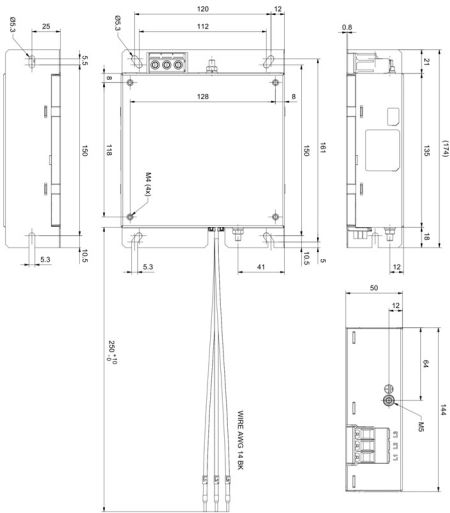
AX-FIC4010-SE



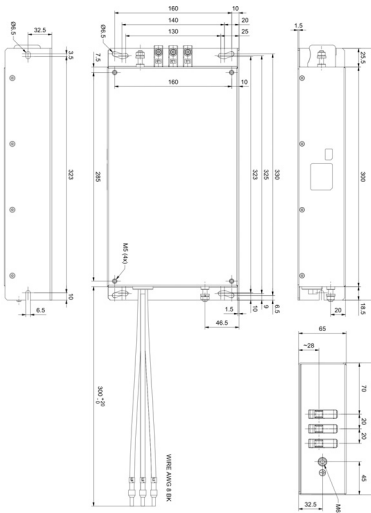
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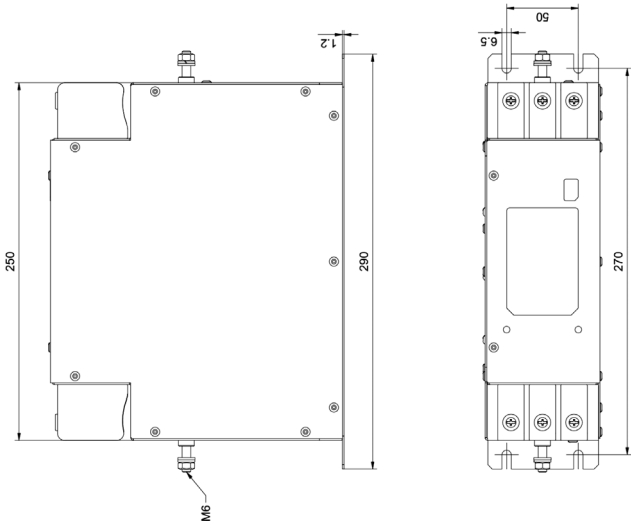
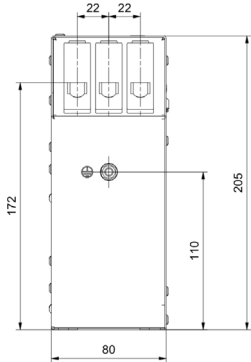
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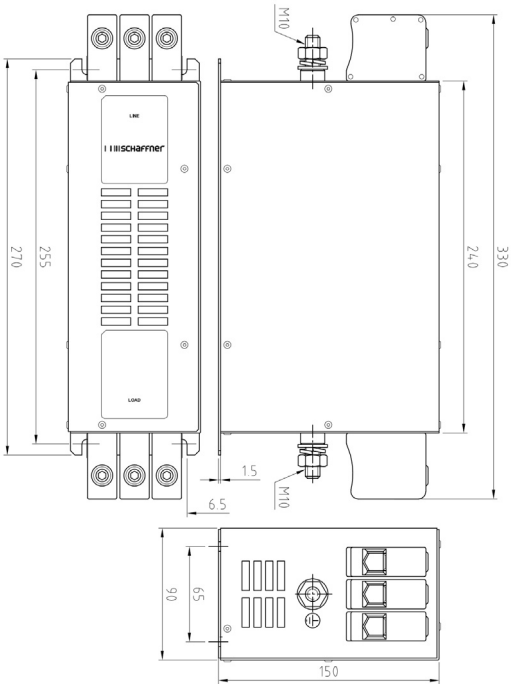
AX-FIC4050-SE



AX-FIC4080-SE



Q2-FIA4100-SE



Note: LL filters has same dimensions than standard ones.

Input AC Reactor

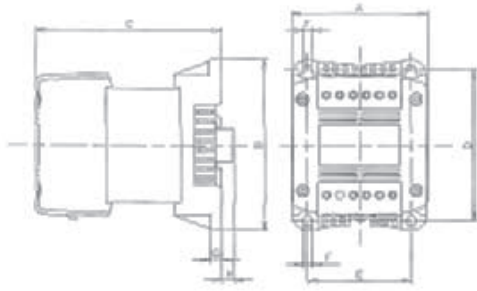


Figure 1

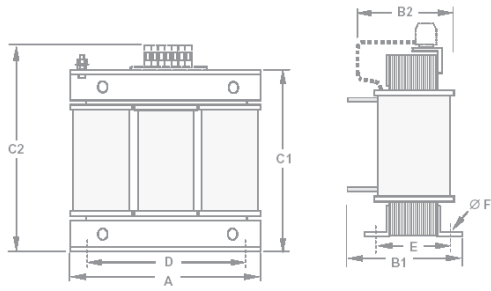


Figure 2

Voltage	Reference	Fig	Dimensions (mm)										Weight (kg)	
			A	B	B2	C	C2	D	E	F	G	H		
Single-phase 200 V	AX-RAI0200070-DE	1	84	113	-	96	-	101	66	5	7.5	2	1.22	
	AX-RAI01700140-DE				116	1.95								
	AX-RAI01200200-DE				131	2.55								
	AX-RAI00630240-DE				116	1.95								
Three-phase 200 V	AX-RAI02800100-DE	2	120	-	70	-	120	80	52	5.5	-	-	1.78	
	AX-RAI00880200-DE				80				62				2.35	
	AX-RAI00350335-DE		180		85		190	140	55	6			5.5	
	AX-RAI00180670-DE				6.5									
	AX-RAI00091000-DE				205								6.5	
Three-phase 400 V	AX-RAI07700042-DE	2	120	-	70	-	120	80	52	5.5	-	-	1.78	
	AX-RAI07700050-DE				80				62				2.35	
	AX-RAI03500090-DE		180		75		195	140	55	6			5.5	
	AX-RAI03500100-DE				85								190	6.5
	AX-RAI01300170-DE				105								205	11.2
	AX-RAI00740335-DE		75		75		6	11.2						
	AX-RAI00360500-DE		6.5											
	AX-RAI00290780-DE		11.2											

DC Reactor

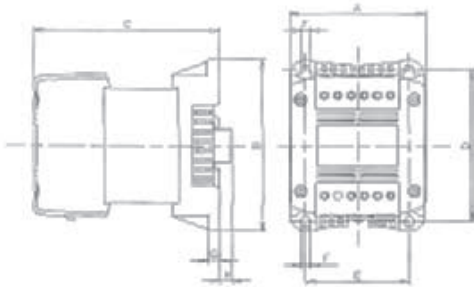


Figure 1

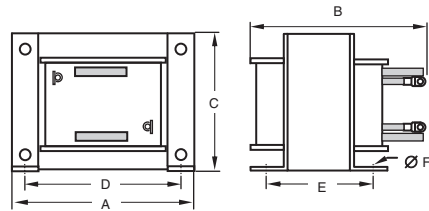
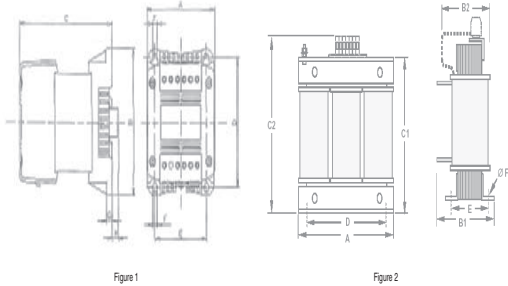


Figure 2

Voltage	Reference	Fig	Dimensions (mm)								Weight (kg)			
			A	B	C	D	E	F	G	H				
200 V	AX-RC10700032-DE	1	84	113	96	101	66	5	7.5	2	1.22			
	AX-RC06750061-DE				105						1.60			
	AX-RC03510093-DE				116						1.95			
	AX-RC02510138-DE		108	135	124	120	82	6.5	9.5	9.5	3.20			
	AX-RC01600223-DE				136						135	94	7	5.20
	AX-RC01110309-DE				146						6.00			
	AX-RC00840437-DE		150	177	160	160	115	-	2	-	11.4			
	AX-RC00590614-DE				183						14.3			
	AX-RC00440859-DE				17.0									
AX-RC00301275-DE	2	195	161	163	185	88	10	-	-	17.0				
400 V	AX-RC43000020-DE	1	84	113	96	101	66	5	7.5	2	1.22			
	AX-RC10100069-DE				116						1.95			
	AX-RC06400116-DE		108	135	133	120	82	6.5	9.5	9.5	3.70			
	AX-RC04410167-DE				136						135	94	7	5.20
	AX-RC03350219-DE		150	177	146	160	115	-	2	-	6.00			
	AX-RC02330307-DE				160						11.4			
	AX-RC01750430-DE				183						14.3			

Output AC Reactor



Voltage	Reference	Dimensions (mm)						Weight (kg)
		A	B2	C2	D	E	F	
200 V	AX-RAO11500026-DE	120	70	120	80	52	5.5	1.78
	AX-RAO07600042-DE		80			62		
	AX-RAO04100075-DE							
	AX-RAO03000105-DE							
	AX-RAO01830160-DE	180	85	195	140	55	6	5.5
	AX-RAO01150220-DE			210				65
	AX-RAO00950320-DE							
	AX-RAO00630430-DE							
	AX-RAO00490640-DE	240	110	275	200	75	16.0	
	AX-RAO00390800-DE							
AX-RAO00330950-DE								
400 V	AX-RAO16300038-DE	120	80	120	80	62	5.5	2.35
	AX-RAO11800053-DE							
	AX-RAO07300080-DE	180	85	195	140	55	6	5.5
	AX-RAO04600110-DE			210				65
	AX-RAO03600160-DE							
	AX-RAO02500220-DE							
	AX-RAO02000320-DE	240	110	275	200	75	16.0	
	AX-RAO01650400-DE							
	AX-RAO01300480-DE							
	AX-RAO00800750-DE							120

Chokes

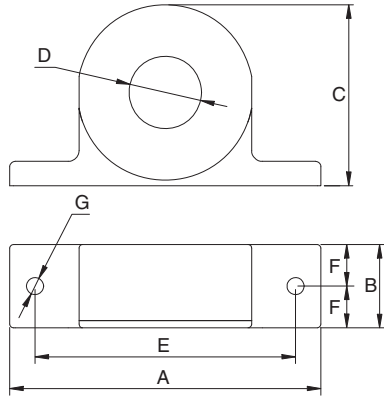


Figure 1

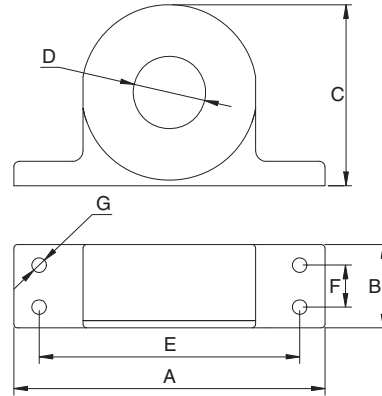
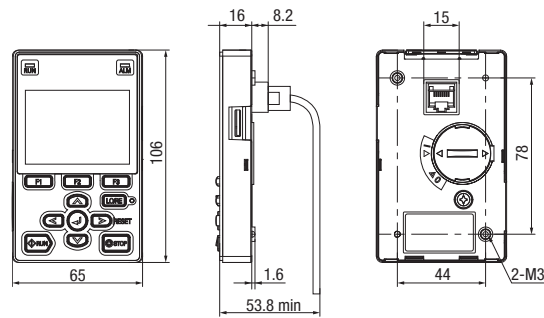


Figure 2

Reference	Fig	D (diameter)	Motor (kW)	Dimensions (mm)								Weight (kg)	
				A	B	C	D	E	F	G (diameter)	H		I
AX-FER2102-PE	1	21	< 2.2	86	24	50	21	70	12	4	-	-	0.09
AX-FER2815-PE		28	< 15	106	25	65	28	90	12.5				0.22
AX-FER5045-PE	2	50	< 45	150	51	112	50	125	30	5			0.53

LCD keypad



Braking resistor

AX-REM00K1200-IE

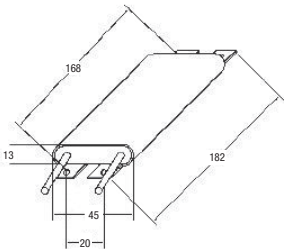


Fig 1

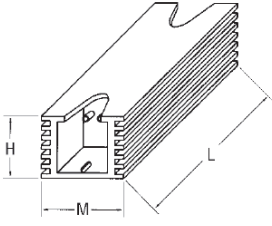


Fig 2

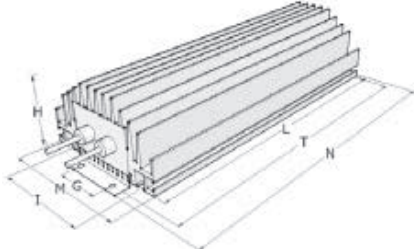


Fig 3

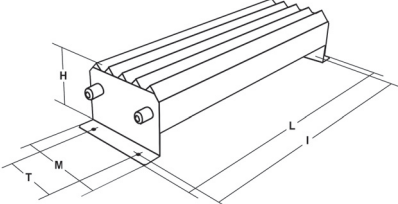


Fig 4

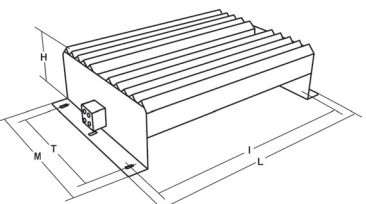
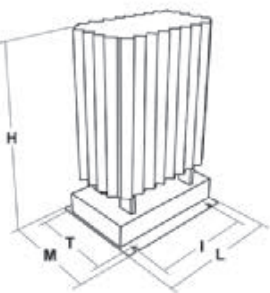


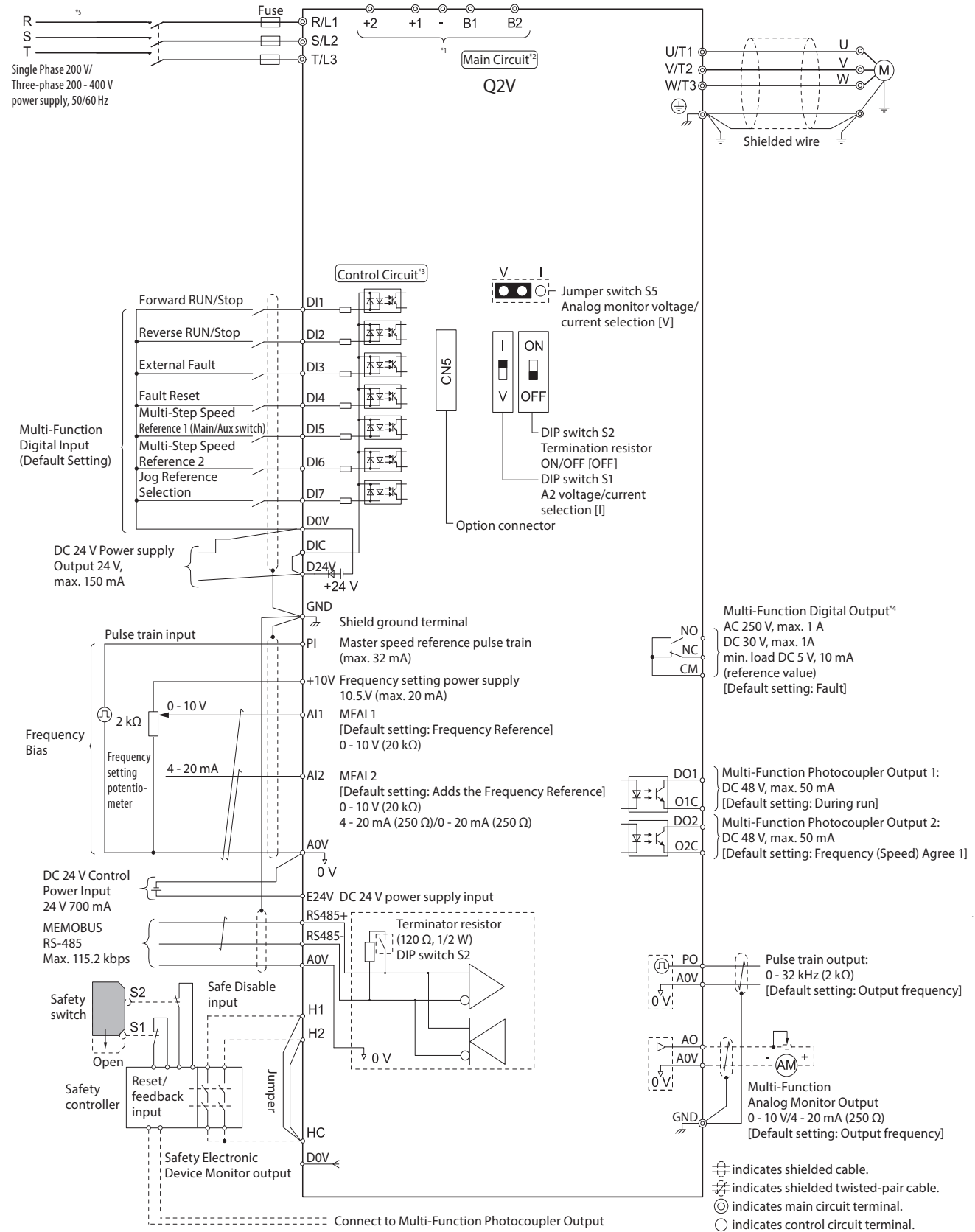
Fig 5



Type	Fig	Dimensions (mm)							Weight (kg)				
		L	H	M	I	T	G	N					
AX-REM00K1400-IE	1	105	27	36	94	-	-	-	0.2				
AX-REM00K2070-IE													
AX-REM00K2120-IE													
AX-REM00K2200-IE													
AX-REM00K4035-IE		200			189					0.425			
AX-REM00K4075-IE													
AX-REM00K5120-IE											260	249	0.58
AX-REM00K6035-IE											320	309	
AX-REM00K6100-IE	2	200	61	100	74.5	216	40	230	1.41				
AX-REM00K9020-IE													
AX-REM00K9070-IE	3	365	73	105	350	70	-	-	4				
AX-REM01K9017-IE													
AX-REM01K9070-IE	4	310	100	240	295	210	-	-	7				
AX-REM02K1017-IE													
AX-REM02K1070-IE		365		350	8								
AX-REM03K5010-IE													
AX-REM03K5035-IE	5	206	350	140	190	50	-	-	8.1				
AX-REM19K0020-IE													

Installation

Standard connections



*1. For three-phase 200 V class and 400 V class drives, use terminals -, +1, +2, B1 and B2 to connect options to the drive. For single-phase 200 V class drives, use terminals -, +1, B1 and B2 to connect options to the drive.

WARNING! Fire Hazard. Only connect factory-recommended devices or circuits to drive terminals B1, B2, -, +1, +2 and +3 terminals. Do not connect AC power to these terminals. Incorrect wiring can cause damage to the drive and serious injury or death from fire.


*2. For circuit protection, the main circuit is separated from the surface case that can touch the main circuit.

*3. The control circuit is a Safety Extra-Low Voltage circuit. Separate this circuit from other circuits with reinforced insulation. Make sure that the Safety Extra-Low Volt-

age circuit is connected as specified.

- *4. Reinforced insulation separates the output terminals from other circuits. Users can also connect circuits that are not Safety Extra-Low Voltage circuits if the drive output is 250 VAC 1 A max. or 30 VDC 1 A maximum.
- *5. Set L8-05 = 1 [In PhaseLoss Selection = Enabled] or set the wiring sequence to prevent input phase loss.

Main circuit

Terminal	Name	Function	
R/L1, S/L2, T/L3	Main circuit power supply input (2001 to 2082 and 4001 to 4060)	Used to connect a power supply	
L/L1, N/L2	Main circuit power supply input (B001 to B018)	Used to connect a power supply	
U/T1, V/T2, W/T3	Drive output	Used to connect a motor	
B1, B2	Braking resistor connection	To connect a braking resistor or braking resistor unit	
+2	DC reactor connection (2001 to 2082 and 4001 to 4060 models)	+1 and +2: To connect a DC reactor ^{*1}	
+1			DC power supply input
-			
	<ul style="list-style-type: none"> • 200 V class: D class grounding (ground to 100 Ω or less) • 400 V class: C class grounding (ground to 10 Ω or less) 	To ground the drive	

*1. Remove the jumper between terminals +1 and +2 to connect a DC reactor.

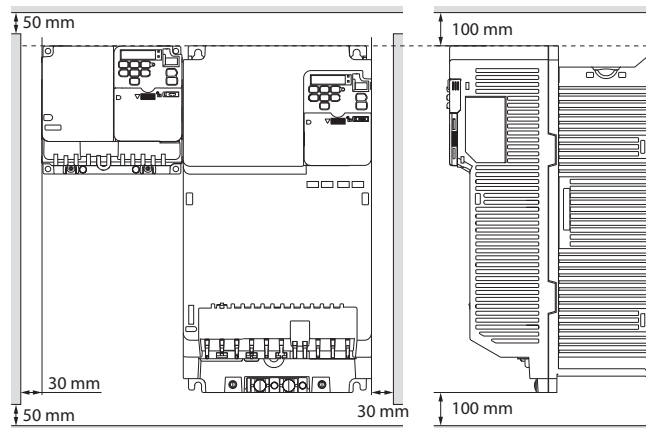
Control circuit

Type	Terminal	Name	Function (Signal level)	
Digital input signals	DI1	Multi-Function Digital Input 1 (ON: Forward run, OFF: Stop)	Photocoupler 24 V, 6 mA Install the wire jumpers between DIC-D24V and DIC-D0V terminals to set the Multi-Function Digital Input power supply. <ul style="list-style-type: none"> • SINK mode: Install a jumper between DIC and D24V terminals. • SOURCE mode: Install a jumper between DIC and D0V terminals. • External power supply: No jumper necessary. 	
	DI2	Multi-Function Digital Input 2 (ON: Reverse run, OFF: Stop)		
	DI3	Multi-Function Digital Input 3 (External fault (N.O.))		
	DI4	Multi-Function Digital Input 4 (Fault reset)		
	DI5	Multi-Function Digital Input 5 (Multi-step speed reference 1)		
	DI6	Multi-Function Digital Input 6 (Multi-step speed reference 2)		
	DI7	Multi-Function Digital Input 7 (Jog reference selection)		
	D0V ^{*1}	MFDI power supply 0 V		24 V, 150 mA max. (for external fuse)
	DIC	MFDI common		
D24V	MFDI power supply +24 VDC			
Safe Disable input	H1	Safe Disable input 1	Remove the jumper between H1-HC and H2-HC terminals to use the Safe Disable input. 24 V, 6 mA ON: Normal operation, OFF: Coasting motor Internal impedance: 4.7 kΩ Minimum OFF time of 3 ms	
	H2	Safe Disable input 2		
	HC ^{*2}	Safe Disable function common		
Master frequency reference	PI	Master speed reference pulse train	Response frequency: 0 to 32 kHz H level duty and voltage: 30 to 70%, 3.5 to 13.2 V L level voltage: 0 to 0.8 V Input impedance: 3 kΩ	
	+10V	Frequency setting power supply	+10.5 V (allowable current max. 20 mA)	
	A11	Multi-Function Analog Input 1 (Frequency reference)	<ul style="list-style-type: none"> • Voltage input or current input: 0 to 10 V/100 % (input impedance: 20 kΩ) 4 to 20 mA/100 %, 0 to 20 mA/100 % (input impedance: 250 Ω) 	
	A12	Multi-Function Analog Input 2 (Frequency reference bias)		
	A0V	Frequency reference common	0 V	
GND	Connecting shielded cable			
Fault relay output	NO	Multi-Function Digital Output, N.O. output	Relay output 30 VDC, 10 mA to 1 A 250 VAC, 10 mA to 1 A Min. load: 5 V, 10 mA (Reference value)	
	NC	Multi-Function Digital Output, N.C. output		
	CM	MFDO common		

Type	Terminal	Name	Function (Signal level)
Multi-function photocoupler output	D01	Multi-Function Photocoupler Output 1 (During Run)	Photocoupler output ^{*3} 48 V, 2 mA to 50 mA
	O1C		
	D02	Multi-Function Photocoupler Output 2 (Speed agree 1)	
	O2C		
Monitor output	PO	Pulse train output (Output frequency)	32 kHz max.
	AO	Analog monitor output (Output frequency)	Select voltage or current output: 0 to 10 V / 0 to 100 % 4 to 20 mA
	A0V	Monitor common	0 V
External power supply input	E24V	External 24 V power supply input	Supplies backup power to the drive control circuit, keypad and option board. 21.6 to 26.4 VDC, 700 mA
	A0V	External 24 V power supply ground	0 V
MEMOBUS/ Modbus ⁴	RS485+	Communication input/output (+)	MEMOBUS/Modbus communication protocol Use an RS-485 cable to connect the drive Maximum 115.2 kbps
	RS485-	Communication output (-)	
	A0V	Shield ground	0 V

- *1. Do not close the circuit between D24V and D0V terminals. Failure to obey will cause damage to the drive.
- *2. Do not close the circuit between HC and D0V terminals. Failure to obey will cause damage to the drive.
- *3. Connect a flywheel diode as shown in when you drive a reactive load such as a relay coil. Make sure that the diode rating is larger than the circuit voltage.
- *4. Select DIP switch S2 to ON to enable the termination resistor in the last drive in a MEMOBUS/Modbus network.

Side by side mounting



Drive watt loss

Single-phase 200 V class

Drive model Q2V-A□	Heavy Duty (HD)					Normal Duty (ND)				
	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)
B001	0.8	10	8	5	13	1.2	2	8	6	14
B002	1.6		10	9	19	1.9		14	11	25
B004	3		14	16	30	3.5		17	17	31
B006	5		18	28	46	6		17	26	43
B010	8	8	31	42	73	9.6		36	50	86
B012	11		41	55	96	12.2		48	60	108
B018	17.6		53	98	151	N/A		49	92	141

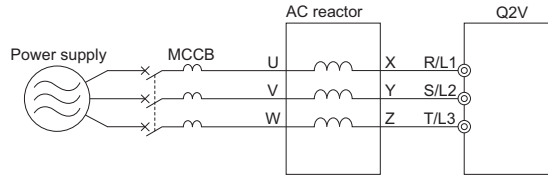
Three-phase 200 V class

Drive model Q2V-A□	Heavy Duty (HD)					Normal Duty (ND)				
	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)
2001	0.8	10	6	5	11	1.2	2	7	5	12
2002	1.6		7	8	15	1.9		9	9	18
2004	3		10	16	26	3.5		11	16	27
2006	5		14	27	41	6		14	25	39
2010	8	8	18	43	61	9.6		25	51	76
2012	11		24	56	80	12.2		30	61	91
2021	17.6		40	108	148	21		52	111	163
2030	25		49	187	236	30		63	240	303
2042	33		60	232	292	42		84	307	391
2056	47		85	318	403	56		109	367	476
2070	60		119	473	592	70		142	534	676
2082	75		148	525	673	82		160	531	691

Three-phase 400 V class

Drive model Q2V-A□	Heavy Duty (HD)					Normal Duty (ND)				
	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)	Rated output current (A)	Carrier frequency (kHz)	Interior unit loss (W)	Cooling fin loss (W)	Total loss (W)
4001	1.2	8	9	11	20	1.2	2	8	7	15
4002	1.8		11	16	27	2.1		13	12	25
4004	3.4		15	31	46	4.1		14	24	38
4005	4.8		18	42	60	5.4		16	32	48
4007	5.6		18	49	67	7.1		20	44	64
4009	7.3		25	65	90	8.9		28	58	86
4012	9.2		32	85	117	11.9		39	83	122
4018	14.8		55	166	221	17.5		52	155	207
4023	18		61	200	261	23.4		86	236	322
4031	24		79	255	334	31		101	284	385
4038	31		95	338	433	38		108	341	449
4044	39		127	442	569	44		137	417	554
4060	45		135	446	581	60		176	490	666

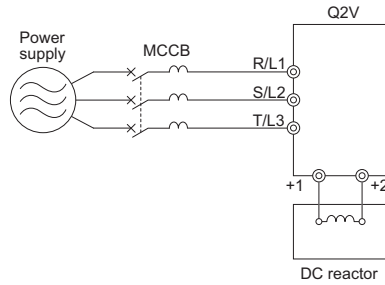
Input AC reactor



Single-phase 200 V				Three-phase 200 V				Three-phase 400 V			
Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)	Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)	Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)
0.75	AX-RAI02000070-DE	7.0	2.0	1.1	AX-RAI02800100-DE	8.0	2.8	0.75	AX-RAI07700042-DE	4.2	7.7
1.1	AX-RAI01700140-DE	14.0	1.7	3.0	AX-RAI00880200-DE	20.0	0.88	1.5	AX-RAI07700050-DE	5.0	7.7
2.2	AX-RAI01200200-DE	20.0	1.2	7.5	AX-RAI00350335-DE	33.5	0.35	2.2	AX-RAI03500090-DE	9.0	3.5
3.0	AX-RAI00630240-DE	24.0	0.63	15.0	AX-RAI00180670-DE	67.0	0.18	3.0	AX-RAI03500100-DE	10.0	3.5
-				22.0	AX-RAI00091000-DE	100.0	0.09	5.5	AX-RAI01300170-DE	17.0	1.3
				-				11.0	AX-RAI00740335-DE	33.5	0.74
								18.5	AX-RAI00360500-DE	50.0	0.36
								30.0	AX-RAI00290780-DE	78.0	0.29

*1. The motor sizes are for heavy duty applications.

DC reactor



200 V class				400 V class			
Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)	Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)
0.37	AX-RC10700032-DE	3.2	10.7	1.5	AX-RC43000020-DE	2.0	43.0
0.75	AX-RC06750061-DE	6.1	6.75	2.2	AX-RC10100069-DE	6.9	10.1
2.2	AX-RC03510093-DE	9.3	3.51	4.0	AX-RC06400116-DE	11.6	6.4
3.0	AX-RC02510138-DE	13.8	2.51	5.5	AX-RC04410167-DE	16.7	4.41
	AX-RC01600223-DE	22.3	1.60	7.5	AX-RC03350219-DE	21.9	3.35
7.5	AX-RC01110309-DE	30.9	1.11	11.0	AX-RC02330307-DE	30.7	2.33
11.0	AX-RC00840437-DE	43.7	0.84	18.5	AX-RC01750430-DE	43.0	1.75
15.0	AX-RC00590614-DE	61.4	0.59	22.0	AX-RC01200644-DE	64.4	1.20
18.5	AX-RC00440859-DE	85.9	0.44		-		
22.0	AX-RC00301275-DE	127.5	0.30				

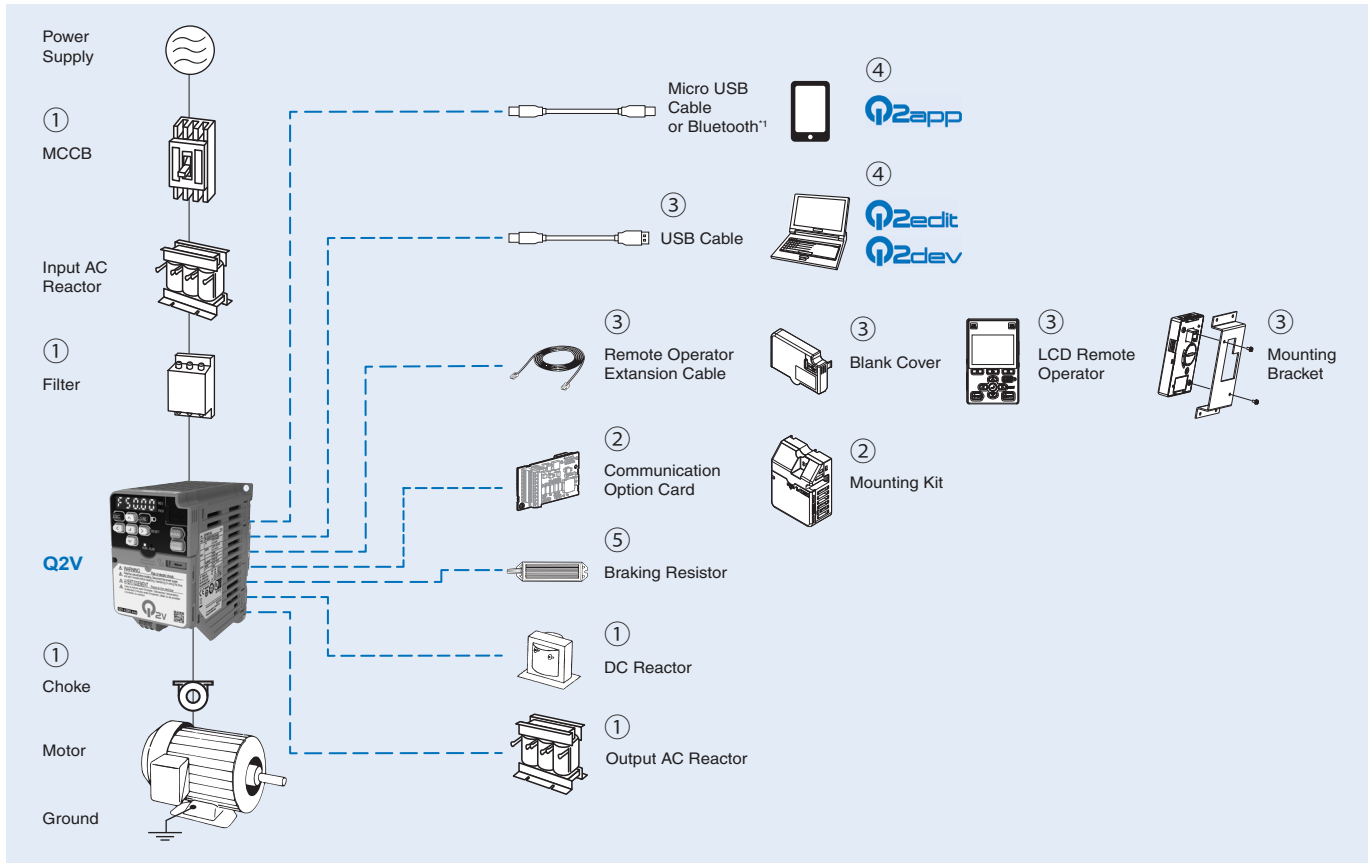
*1. The motor sizes are for heavy duty applications.

Output AC reactor

200 V class				400 V class			
Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)	Max. applicable motor output (kW) ^{*1}	Reference	Current value (A)	Inductance (mH)
0.37	AX-RAO11500026-DE	2.6	11.5	0.75	AX-RAO16300038-DE	3.8	16.3
0.75	AX-RAO07600042-DE	4.2	7.60	1.5	AX-RAO11800053-DE	5.3	11.8
1.1	AX-RAO04100075-DE	7.5	4.10	2.2	AX-RAO07300080-DE	8.0	7.3
2.2	AX-RAO03000105-DE	10.5	3.00	4.0	AX-RAO04600110-DE	11.0	4.6
3.0	AX-RAO01830160-DE	16.0	1.83	5.5	AX-RAO03600160-DE	16.0	3.6
5.5	AX-RAO01150220-DE	22.0	1.15	7.5	AX-RAO02500220-DE	22.0	2.5
7.5	AX-RAO00950320-DE	32.0	0.95	11.0	AX-RAO02000320-DE	32.0	2.0
11.0	AX-RAO00630430-DE	43.0	0.63	15.0	AX-RAO01650400-DE	40.0	1.65
15.0	AX-RAO00490640-DE	64.0	0.49	22.0	AX-RAO01300480-DE	48.0	1.3
18.5	AX-RAO00390800-DE	80.0	0.39	30.0	AX-RAO00800750-DE	75.0	0.8
22.0	AX-RAO00330950-DE	95.0	0.33				

*1. The motor sizes are for heavy duty applications.

Ordering information



*1 With optional LCD remote operator model with Bluetooth.

Q2V drive

Voltage	Specifications				Model	
	Heavy Duty (HD)		Normal Duty (ND)		Built-in EMC filter	Without built-in EMC filter
	Max motor (kW)	Rated current (A)	Max motor (kW)	Rated current (A)		
Single-phase 200 V	0.1	0.8	0.18	1.2	Q2V-AB001-AAA	Q2V-AB001-BAA
	0.25	1.6	0.37	1.9	Q2V-AB002-AAA	Q2V-AB002-BAA
	0.55	3.0	0.75	3.5	Q2V-AB004-AAA	Q2V-AB004-BAA
	1.1	5.0	1.1	6.0	Q2V-AB006-AAA	Q2V-AB006-BAA
	1.5	8.0	2.2	9.6	Q2V-AB010-AAA	Q2V-AB010-BAA
	2.2	11.0	3.0	12.2	Q2V-AB012-AAA	Q2V-AB012-BAA
	4.0	17.6	-	-	-	Q2V-AB018-BAA
Three-phase 200 V	0.1	0.8	0.18	1.2	Q2V-A2001-AAA	Q2V-A2001-BAA
	0.25	1.6	0.37	1.9	Q2V-A2002-AAA	Q2V-A2002-BAA
	0.55	3.0	0.75	3.5	Q2V-A2004-AAA	Q2V-A2004-BAA
	1.1	5.0	1.1	6.0	Q2V-A2006-AAA	Q2V-A2006-BAA
	1.5	8.0	2.2	9.6	Q2V-A2010-AAA	Q2V-A2010-BAA
	2.2	11	3.0	12.2	Q2V-A2012-AAA	Q2V-A2012-BAA
	4.0	17.6	5.5	21	Q2V-A2021-AAA	Q2V-A2021-BAA
	5.5	25	7.5	30	Q2V-A2030-AAA	Q2V-A2030-BAA
	7.5	33	11	42	Q2V-A2042-AAA	Q2V-A2042-BAA
	11	47	15	56	Q2V-A2056-AAA	Q2V-A2056-BAA
	15	60	18.5	70	Q2V-A2070-AAA	Q2V-A2070-BAA
	18.5	75	22	82	Q2V-A2082-AAA	Q2V-A2082-BAA

Specifications					Model	
Voltage	Heavy Duty (HD)		Normal Duty (ND)		Built-in EMC filter	Without built-in EMC filter
	Max motor (kW)	Rated current (A)	Max motor (kW)	Rated current (A)		
Three-phase 400 V	0.37	1.2	0.37	1.2	Q2V-A4001-AAA	Q2V-A4001-BAA
	0.55	1.8	0.75	2.1	Q2V-A4002-AAA	Q2V-A4002-BAA
	1.1	3.4	1.5	4.1	Q2V-A4004-AAA	Q2V-A4004-BAA
	1.5	4.8	2.2	5.4	Q2V-A4005-AAA	Q2V-A4005-BAA
	2.2	5.6	3.0	7.1	Q2V-A4007-AAA	Q2V-A4007-BAA
	3.0	7.3	4.0	8.9	Q2V-A4009-AAA	Q2V-A4009-BAA
	4.0	9.2	5.5	11.9	Q2V-A4012-AAA	Q2V-A4012-BAA
	5.5	14.8	7.5	17.5	Q2V-A4018-AAA	Q2V-A4018-BAA
	7.5	18	11	23.4	Q2V-A4023-AAA	Q2V-A4023-BAA
	11	24	15	31	Q2V-A4031-AAA	Q2V-A4031-BAA
	15	31	18.5	38	Q2V-A4038-AAA	Q2V-A4038-BAA
18.5	39	22	44	Q2V-A4044-AAA	Q2V-A4044-BAA	
22	45	30	60	Q2V-A4060-AAA	Q2V-A4060-BAA	

① Line filters

Drive		Standard line filter		Low leakage line filter	
Voltage	Model Q2V-A□	Reference	Current (A)	Reference	Current (A)
Single-phase 200 V	B001/B002/B004	AX-FIC1010-SE	7.3	AX-FIC1010-SE-LL	7.3
	B006	AX-FIC1020-SE	13.8	AX-FIC1020-SE-LL	13.8
	B010	AX-FIM1024-SE ^{*1}	24	AX-FIM1024-SE-LL ^{*1}	24
		AX-FIC1030-SE ^{*2}	24	AX-FIC1030-SE-LL ^{*2}	24
	B012	AX-FIC1030-SE	24	AX-FIC1030-SE-LL	24
	B018	AX-FIC1040-SE	35	AX-FIC1040-SE-LL	35
Three-phase 200 V	2001/2002/2004/2006	AX-FIC4010-SE	9.4	AX-FIC4010-SE-LL	9.4
	2010/2012	AX-FIC4015-SE	14	AX-FIC4015-SE-LL	14
	2021	AX-FIC4030-SE	24	AX-FIC4030-SE-LL	24
	2030	AX-FIC4050-SE	44	AX-FIC4050-SE-LL	44
	2042/2056/2070	AX-FIC4080-SE	81	AX-FIC4080-SE-LL	81
	2082	Q2-FIA4100-SE	100	—	—
Three-phase 400 V	4001/4002/4004	AX-FIC4005-SE	4.3	AX-FIC4005-SE-LL	4.3
	4005/4007/4009	AX-FIC4010-SE	9.4	AX-FIC4010-SE-LL	9.4
	4012	AX-FIC4015-SE	14	AX-FIC4015-SE-LL	14
	4018/4023	AX-FIC4030-SE	24	AX-FIC4030-SE-LL	24
	4031/4038	AX-FIC4050-SE	44	AX-FIC4050-SE-LL	44
	4044/4060	AX-FIC4080-SE ^{*2}	81	AX-FIC4080-SE-LL	81

*1. No UL approved

*2. No footprint

Note: 200 V Three-phase filters are not footprint.

① Input AC reactors

Single-phase 200 V		Three-phase 200 V		Three-phase 400 V	
Model Q2V-A□	Input AC reactor	Model Q2V-A□	Input AC reactor	Model Q2V-A□	Input AC reactor
B001/B002/B004	AX-RAI02000070-DE	2001/2002/2004/2006	AX-RAI02800100-DE	4001/4002	AX-RAI07700042-DE
B006	AX-RAI01700140-DE	2010/2012	AX-RAI00880200-DE	4004	AX-RAI07700050-DE
B010	AX-RAI01200200-DE	2021/2030	AX-RAI00350335-DE	4005	AX-RAI03500090-DE
B012	AX-RAI00630240-DE	2042/2056	AX-RAI00180670-DE	4007	AX-RAI03500100-DE
B018	—	2070/2082	AX-RAI00091000-DE	4009/4012	AX-RAI01300170-DE
				4018/4023	AX-RAI00740335-DE
				4031/4038	AX-RAI00360500-DE
				4044/4060	AX-RAI00290780-DE

① DC reactors

Single-phase 200 V		Three-phase 200 V		Three-phase 400 V	
Model Q2V-A□	DC reactor	Model Q2V-A□	DC reactor	Model Q2V-A□	DC reactor
B001/B002	AX-RC10700032-DE	2001/2002/2004/2006	AX-RC06750061-DE	4001/4002/4004	AX-RC43000020-DE
B004	AX-RC06750061-DE	2010	AX-RC03510093-DE	4005	AX-RC10100069-DE
B006	AX-RC03510093-DE	2012	AX-RC02510138-DE	4007/4009	AX-RC06400116-DE
B010	AX-RC02510138-DE	2021/2030	AX-RC01110309-DE	4012	AX-RC04410167-DE
B012	AX-RC01600223-DE	2042	AX-RC00840437-DE	4018	AX-RC03350219-DE
B018	—	2056	AX-RC00590614-DE	4023	AX-RC02330307-DE
		2070	AX-RC00440859-DE	4031/4038	AX-RC01750430-DE
		2082	AX-RC00301275-DE	4044	AX-RC01200644-DE

① Output AC reactors

Single-phase 200 V		Three-phase 200 V		Three-phase 400 V	
Model Q2V-A□	Output AC reactor	Model Q2V-A□	Output AC reactor	Model Q2V-A□	Output AC reactor
B001/B002	AX-RAO11500026-DE	2001/2002/2004	AX-RAO07600042-DE	4001/4002	AX-RAO16300038-DE
B004	AX-RAO07600042-DE	2006	AX-RAO04100075-DE	4004	AX-RAO11800053-DE
B006	AX-RAO04100075-DE	2010	AX-RAO03000105-DE	4005	AX-RAO07300080-DE
B010	AX-RAO03000105-DE	2012/2021	AX-RAO01150220-DE	4007/4009	AX-RAO04600110-DE
B012	AX-RAO01830160-DE	2030	AX-RAO00950320-DE	4012	AX-RAO03600160-DE
B018	AX-RAO01150220-DE	2042	AX-RAO00630430-DE	4018	AX-RAO02500220-DE
-		2056	AX-RAO00490640-DE	4023	AX-RAO02000320-DE
		2070	AX-RAO00390800-DE	4031	AX-RAO01650400-DE
		2082	AX-RAO00330950-DE	4038/4044	AX-RAO01300480-DE
		-			

Note: This table corresponds with HD rating. When ND is used, please choose the reactor for the next size drive.

① Chokes

Model	Diameter	Description
AX-FER2102-PE	21	For 2.2 KW motors or below
AX-FER2815-PE	28	For 15 KW motors or below
AX-FER5045-PE	50	For 45 KW motors or below

② Option cards

Type	Model	Description	Function
Mounting kit	JOHB-Q2V	Option card enclosure	Enclosure to install a communication option card on a Q2V.
Communication option cards	SI-ES3	EtherCAT	Used for running or stopping the drive, setting or referencing parameters, and monitoring output frequency, output current, or similar items through EtherCAT communication with the host controller.
	SI-EP3	PROFINET	Used for running or stopping the drive, setting or referencing parameters, and monitoring output frequency, output current, or similar items through PROFINET communication with the host controller.
	SI-EN3	EtherNet/IP	Used for running or stopping the drive, setting or referencing parameters, and monitoring output frequency, output current, or similar items through EtherNet/IP communication with the host controller.
	SI-EN3/D	EtherNet/IP Dual-Port	
	SI-EL3	POWERLINK	Used for running or stopping the drive, setting or referencing parameters, and monitoring output frequency, output current, or similar items through POWERLINK communication with the host controller.
Mounting kit + communication option card	SI-ES3/Q2V	Option card enclosure + EtherCAT option board	Enclosure with the EtherCAT communication card ready to be installed on a Q2V.

③ Accessories

Description	Functions	Model	
LCD remote operator	Standard model	JVOP-KPLCA04AEZ	
	Model with Bluetooth	JVOP-KPLCC04ABZ	
Blank cover	This cover is required when using a LCD remote operator	JVOP-KPBCH04AAZ	
USB cable	Mini USB to USB cable	AX-CUSBM002-E	
Remote operator cable	3 meters cable to connect the keypad and drive	3G3AX-CAJOP300-EE	
Keypad mounting bracket	This bracket is required to mount the LCD Remote Operator outside an enclosure panel	Screw type	900-192-933-001
		Nut type	900-192-933-002

④ Software tools

Description	Functions	Model
Software tools	Software tool to configure drives and manage parameters	Q2edit
	Software tool to do advanced drive programming	Q2dev
	Software tool to configure drives and manage parameters for mobile devices (Android & iOS)	Q2app

⑤ Braking resistor

Drive model Q2V-A□					Braking resistor (3 % ED, 10 sec max)				Braking resistor (10 % ED, 10 sec max)										
Voltage	Max. applicable motor kW	Single-phase	Three-phase	Connectable min. resistance	Model	Specifications		Qty	Model	Specifications		Qty							
200 V	0.1	B001	2001	300 Ω	AX-REM00K1400-IE	100 W	400 Ω	1	AX-REM00K1400-IE	100 W	400 Ω	1							
	0.25	B002	2002																
	0.55	B004	2004	200 Ω	AX-REM00K1200-IE	200 Ω	AX-REM00K1200-IE		200 Ω										
	1.1	B006	2006	120 Ω	AX-REM00K2200-IE		200 W			AX-REM00K4075-IE	400 W		75 Ω						
	1.5	B010	2010	60 Ω	AX-REM00K2070-IE	200 W	70 Ω		AX-REM00K4075-IE	400 W	75 Ω								
	2.2	B012	2012	9.6 Ω	AX-REM00K4035-IE	400 W	35 Ω		AX-REM00K6035-IE	600 W	35 Ω		AX-REM00K6035-IE	600 W	35 Ω				
	4.0	B018	2021						AX-REM00K9020-IE	900 W	20 Ω		AX-REM00K9020-IE	900 W	20 Ω	AX-REM00K9020-IE	900 W	20 Ω	
	5.5	-	2030						AX-REM01K9017-IE	1900 W	17 Ω		AX-REM01K9017-IE	1900 W	17 Ω	AX-REM01K9017-IE	1900 W	17 Ω	
	7.5		2042						AX-REM02K1017-IE	2100 W	10 Ω		AX-REM02K1017-IE	2100 W	10 Ω	AX-REM02K1017-IE	2100 W	10 Ω	
	11		2056						AX-REM03K5010-IE	3500 W	10 Ω		AX-REM03K5010-IE	3500 W	10 Ω	AX-REM03K5010-IE	3500 W	10 Ω	
	15		2070																
	18.5		2082																
	0.37		-						4001	750 Ω	AX-REM00K1400-IE		100 W	400 Ω	2	AX-REM00K1400-IE	100 W	400 Ω	2
	0.55								4002										
1.1	4004							510 Ω	AX-REM00K2200-IE	200 W	200 Ω	1	AX-REM00K2200-IE	200 W	200 Ω	1			
1.5	4005	240 Ω		AX-REM00K5120-IE	500 W	120 Ω	AX-REM00K6100-IE	600 W					100 Ω						
2.2	4007	200 Ω		AX-REM00K6100-IE	600 W	100 Ω	AX-REM00K9070-IE	900 W					70 Ω						
3.0	4009	100 Ω		AX-REM01K9070-IE	1900 W	70 Ω	AX-REM01K9070-IE	1900 W					70 Ω						
4.0	4012	32 Ω		AX-REM02K1070-IE	2100 W	35 Ω	AX-REM02K1070-IE	2100 W					35 Ω						
5.5	4018			AX-REM03K5035-IE	3500 W	35 Ω	AX-REM03K5035-IE	3500 W					35 Ω						
7.5	4023	20 Ω		AX-REM19K0020-IE	19000 W	20 Ω	AX-REM19K0020-IE	19000 W					20 Ω						
11	4031			AX-REM00K6035-IE	600 W	35 Ω	AX-REM00K6035-IE	600 W					35 Ω						
15	4038			AX-REM00K9020-IE	900 W	20 Ω	AX-REM00K9020-IE	900 W					20 Ω						
18.5	4044			19.2 Ω															
22	4060																		

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
 To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.